

EE101 Lecture #21 May 2, 2018

- Quiz 8 on March 5, 2018
- coverage chap 6 & 7 First-order circuits
  - Thevenin's equivalent circuit
  - Norton's "
  - $C_{eff}$ ,  $L_{eff}$ ,  $R_{eff}$
  - solution of RC circuits - say step inputs  $v(t) = V u(t)$  or  $i(t) = I u(t)$



Course Grading

- 1) Average of best 7 quiz scores scaled to 100 20%
- 2) Mid-term Examination 30%
- 3) Final Examination 50%  
(March 20, 2 pages of formulas allowed)

**Prob. 1.20**

Find the power absorbed in each element (1-6)

	v	i	power absorbed
1			
2			
3			
4			
5			
6			

KCL at  $\otimes$ :  
 $i_1 + i_2 + i_3 + i_4 = 0$   
 with outgoing +

KCL at  $\otimes$ : outgoing + | incoming -  
 $i_1 - i_2 - i_3 = 0$   
 $-i_1 + i_2 + i_3 = 0$  (same)  
 $x(-1) \rightarrow i_1 - i_2 - i_3 = 0$

**Quiz 7 Solution**  $1:n = 1:\frac{1}{5}$

Power delivered = ?

For max. power transfer,  $R_2 = R_{eff}$  or

$$400 = \frac{R_p \cdot 800}{R_p + 800} \Rightarrow (R_p + 800) 400 = R_p 800$$

thus  $R_p = 800 \Omega$

next average power delivered to  $R = 32 \Omega$  ?

$$v_A(t) = v_s(t) \frac{R_p (=400)}{400 + (R_{eff} = 400)} = \frac{110 \sin \omega t}{2} = 55 \sin \omega t$$

$$v_A(t) = \frac{1}{5} v_s(t) = 11 \sin \omega t$$

$$P_{32\Omega}(t) = \frac{v_A^2(t)}{32} = \frac{121 \sin^2 \omega t}{32} = \frac{121}{32} \sin^2 \omega t$$

$$\sin^2 \omega t = \frac{1}{2} - \frac{1}{2} \cos 2\omega t$$

$$P_{avg} = \frac{1}{T} \int_0^T \frac{121}{32} \sin^2 \omega t dt = \frac{121}{32} \frac{1}{T} \int_0^T (\frac{1}{2} - \frac{1}{2} \cos 2\omega t) dt$$

$$= \frac{121}{32 \times 2} = \boxed{1.89 \text{ W}}$$

" Science News "

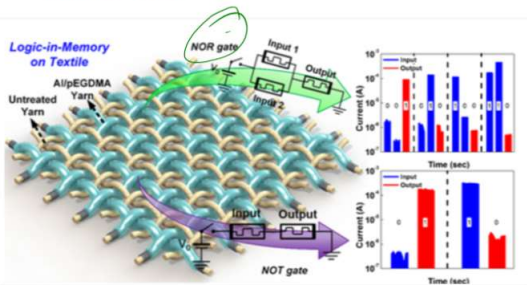


Figure 3. Schematic view of the fabricated device with logic circuits and electrical measured data of the NOR and NOT gate on fabric.

PEGDMA = poly Ethylene Glycol Dimeth Acrylate

Functional Circuitry on Commercial Fabric via Textile-Compatible Nanoscale Film Coating Process for Fibertronics

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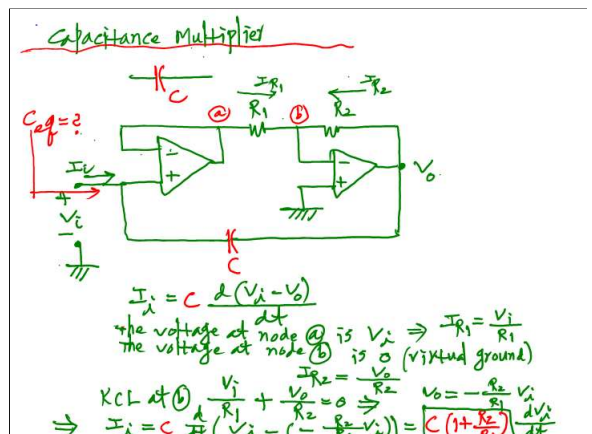
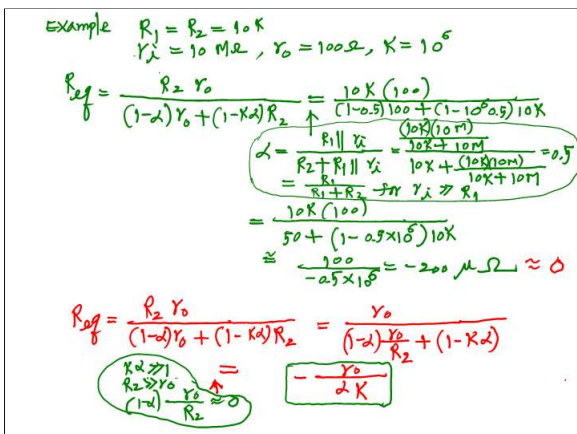
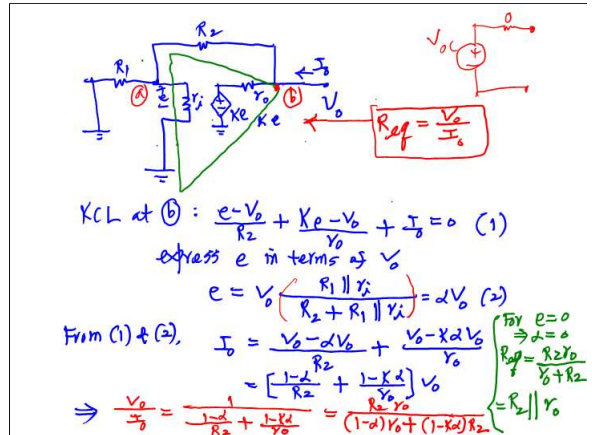
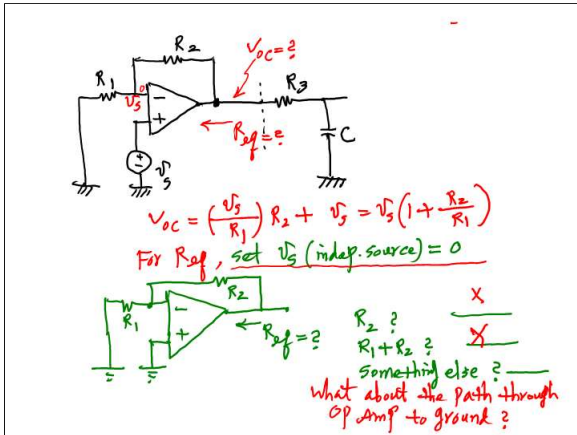
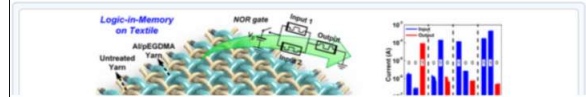
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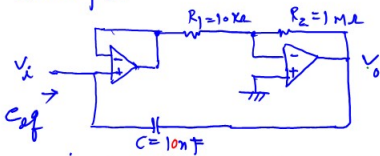
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Abstract

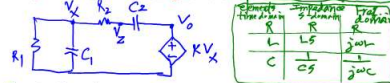


Example



$$C_{eq} = C \left( 1 + \frac{R_2}{R_1} \right) = 10nF \left( 1 + \frac{100k}{10k} \right) = 1.01 \mu F$$

Principle of Wien-Bridge Oscillator



In s-domain

$$V_X(s) \left( \frac{1}{R_1} + C_1 s \right) = \frac{(K-1) V_X(s)}{R_2 + \frac{1}{C_2 s}}$$

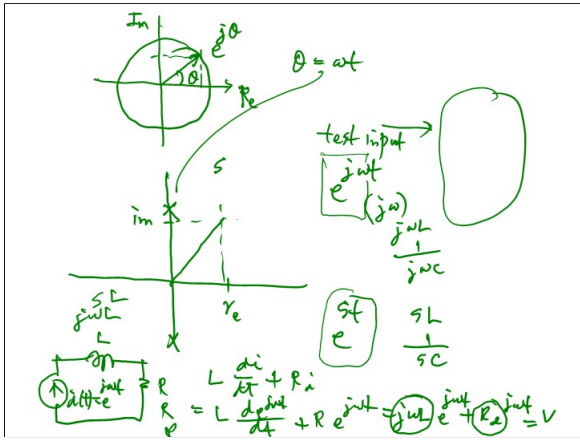
$$V_X(s) \left( \frac{1}{R_1} + C_1 s \right) (R_2 + \frac{1}{C_2 s}) = (K-1) V_X(s)$$

$$\times R_1 \cdot C_2 s \Rightarrow V_X(s) (1 + R_1 C_1 s) (R_2 C_2 s + 1) = (K-1) R_1 C_2 s$$

$$(R_1 C_1 + R_2 C_2) s + R_1 R_2 C_1 C_2 s^2 + 1 = (K-1) R_1 C_2 s$$

$$R_1 R_2 C_1 C_2 s^2 + (R_1 C_1 + R_2 C_2 - (K-1) R_1 C_2) s + 1 = 0$$

(set to zero) → **Backhausen criterion**



then  $R_1 R_2 C_1 C_2 s^2 + 1 = 0$

$$s = \pm \sqrt{\frac{-1}{R_1 R_2 C_1 C_2}} = \pm j \sqrt{\frac{1}{R_1 R_2 C_1 C_2}} = \pm j \omega_0$$

x + jω<sub>0</sub>  
x - jω<sub>0</sub>

$$R_1 C_1 + R_2 C_2 - (K-1) R_1 C_2 = 0$$

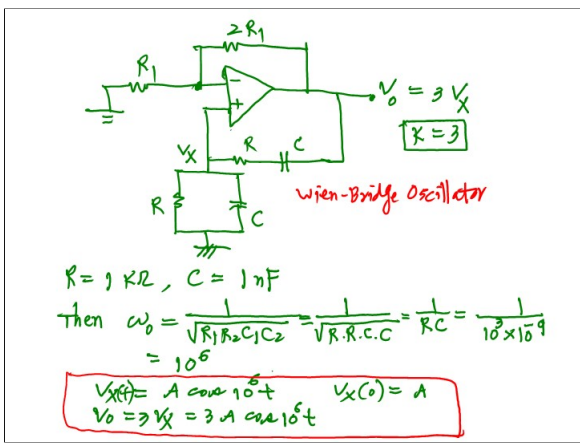
$$R_1 C_1 + R_2 C_2 = (K-1) R_1 C_2$$

$$K = \frac{R_1 C_1 + R_2 C_2}{R_1 C_2} + 1$$

Backhausen Criterion is met with this K value!

If  $R_1 = R_2 = R, C_1 = C_2 = C$ , then

$$K = \frac{2RC}{RC} + 1 = 3$$

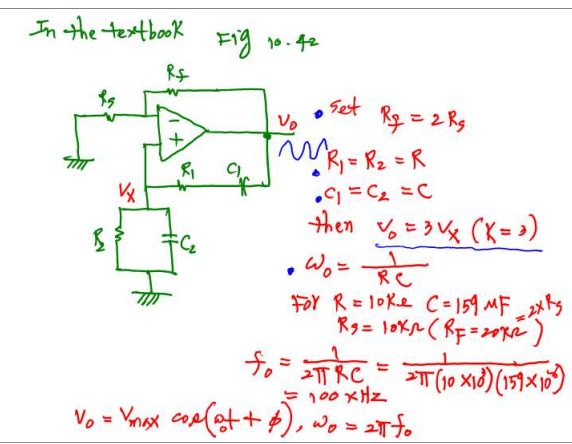


$R = 10k\Omega, C = 10nF$

Then  $\omega_0 = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}} = \frac{1}{\sqrt{R \cdot R \cdot C \cdot C}} = \frac{1}{RC} = \frac{1}{10^4 \times 10^{-8}} = 10^5$

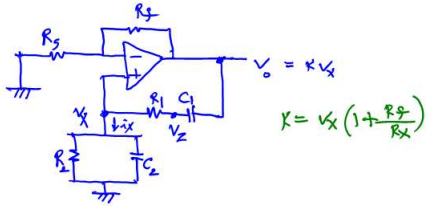
$$V_X(t) = A \cos \omega_0 t \quad V_X(0) = A$$

$$V_0 = 3 V_X = 3 A \cos 10^5 t$$



In the textbook Fig 10.42

- Set  $R_f = 2R_f$
- $R_1 = R_2 = R$
- $C_1 = C_2 = C$
- then  $V_0 = 3 V_X (K=3)$
- $\omega_0 = \frac{1}{RC}$
- For  $R = 10k\Omega, C = 159 \mu F = 159 \times 10^{-6} s$
- $R_f = 10k\Omega (R_f = 20k\Omega)$
- $f_0 = \frac{1}{2\pi RC} = \frac{1}{2\pi (10 \times 10^3) (159 \times 10^{-6})} = 100 \text{ Hz}$
- $V_0 = V_{max} \cos(\omega_0 t + \phi), \omega_0 = 2\pi f_0$



$$K = V_o \left(1 + \frac{R_3}{R_1}\right)$$

$$\dot{V}_x = \frac{V_x}{R_2} + C_2 \frac{dV_x}{dt} = C_1 \frac{d}{dt} (K V_x - V_o) \quad (1)$$

$$V_o = V_x + \left(\frac{V_x}{R_2} + C_2 \frac{dV_x}{dt}\right) R_1 \quad (2)$$

From (1) & (2)

$$\frac{V_x}{R_2} + C_2 \frac{dV_x}{dt} = C_1 \frac{d}{dt} \left[ (K-1) V_x - \left(\frac{V_x}{R_2} + C_2 \frac{dV_x}{dt}\right) R_1 \right]$$

$$\times R_2 \rightarrow V_x + R_2 C_2 \frac{dV_x}{dt} = C_1 (K-1) R_2 \frac{dV_x}{dt} - R_1 R_2 C_1 C_2 \frac{d^2 V_x}{dt^2}$$

which is  $R_1 R_2 C_1 C_2 \frac{d^2 V_x}{dt^2} + (R_1 C_1 + R_2 C_2 - C_1 (K-1) R_2) \frac{dV_x}{dt} + V_x = 0$

If we set the first derivative part to zero,

i.e.  $R_1 C_1 + R_2 C_2 - (K-1) R_2 C_1 = 0$ ,  
(characteristic criterion)

then  $R_1 R_2 C_1 C_2 \frac{d^2 V_x}{dt^2} + V_x = 0 \quad (*)$

$V_x = A \cos(\omega_0 t + \phi)$  can satisfy the equation (\*)

$$-R_1 R_2 C_1 C_2 \omega_0^2 A \cos(\omega_0 t + \phi) + A \cos(\omega_0 t + \phi) = 0$$

$$\Rightarrow R_1 R_2 C_1 C_2 \omega_0^2 = 1$$

$$\omega_0^2 = \frac{1}{R_1 R_2 C_1 C_2}$$

$$\omega_0 = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}, \quad \omega_0 = \frac{1}{RC} \text{ if } R_1=R_2=R, C_1=C_2=C$$

$$V_x = A \cos(\omega_0 t + \phi), \quad V_o = K V_x = \left(1 + \frac{R_3}{R_1}\right) \times A \cos(\omega_0 t + \phi)$$